ON THE MAXIMAL NUMBER OF SOLUTIONS OF A PROBLEM IN LINEAR INEQUALITIES

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ABSTRACT

The problem y = Ax + c, $x \ge 0$, $y \ge 0$, (x, y) = 0 is considered, where the square real matrix A and the real vector c are the data and a solution is a pair of vectors x, y. Under certain conditions on the matrix A there exists a solution for every vector c, but it cannot be unique for every c. We prove that under these conditions the maximal number of solutions is $2^n - 1$.

1. Introduction

In a recent paper [1], A. W. Ingleton has studied the following problem in the theory of linear inequalities: Given a square real matrix $A = (a_{ij})_{i,j=1}^n$ and an *n*-dimensional real vector $c = (c_i)_{i=1}^n$, under what conditions on the matrix A do there exist solutions of the system:

(*)
$$y = Ax + c, x \ge 0, y \ge 0, (x, y) = 0$$

for every vector c? and when is the solution of the system (*) unique? Clearly, by a solution we mean a pair of vectors x and y which satisfy (*). (x, y) stands for the inner product of the two vectors in the n-dimensional vector space V.

Finding solutions of the system (*) is known in mathematical programming as the linear complementarity problem, see [2].

In [1], Ingleton has proved that under certain conditions there exists a solution of (*) for every vector c, but it cannot be unique for every c, and conjectured that under these "certain conditions", the maximal number of solutions of (*) is $2^{n}-1$.

The purpose of the present note is to answer in part this conjecture.

2. Definitions and notations

Let V be a real vector space of finite dimension n > 0 endowed with an inner product denoted by (x, y) and e_1, e_2, \dots, e_n an orthonormal basis of V (which is assumed to remain fixed throughout except where otherwise stated). A vector

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 $x \in V$ will be called non-negative, written $x \ge 0$ if $(x, e_i) \ge 0$ for all $i = 1, 2, \dots, n$; semi-positive, written $x \ge 0$ if $x \ge 0$ and $x \ne 0$; and positive, written x > 0 if $(x, e_i) > 0$ for all $i = 1, 2, \dots, n$.

The range of a linear transformation $A: V \to V$ will be denoted by R(A), its rank by ρA , and its adjoint by A^* (i.e. $(Ax, y) = (x, A^*y)$ for all $x, y \in V$).

Given any subset I of $\{1, 2, \dots, n\}$ we denote by

|I| the number of elements in I,

 V_I the subspace spanned by $\{e_i: i \in I\}$,

 A_I the restriction of A to V_I ,

 P_I the orthogonal projection of V onto V_I ,

 A_{II} the linear transformation $P_IA_I: V_I \to V_I$,

 x_I the vector $P_I x (x \in V)$.

(When $I=\phi$, V_{ϕ} is the zero vector space, and for any $A,A_{\phi\phi}$ is the unique map $V_{\phi} \rightarrow V_{\phi}$ which is invertible and has determinant unity).

DEFINITION. The linear transformation A will be called adequate (with respect to a given basis) if for every subset I of $\{1, 2, \dots, n\}$,

- 1) det $A_{II} \ge 0$
- 2) det $A_{II} = 0 \Rightarrow \rho A_I < |I|$
- 3) det $A_{II} = 0 \Rightarrow \rho A_I^* < |I|$

The matrix of an adequate linear transformation A (with respect to a given basis) has therefore the following properties:

- a) all principal minors of A are non-negative,
- b) if some principal minor of A vanishes then the corresponding rows of A are linearly dependent and so are the corresponding columns.

3. Sufficient conditions for the existence and uniqueness of solutions

The following theorems, corollary and lemma were proved by Ingleton in [1]:

THEOREM 1. If $A: V \to V$ is an adequate linear transformation then for every $c \in R(A)$ there is exactly one $y \in V$ such that, for some x, y = Ax + c, $x \ge 0, y \ge 0, (x, y) = 0$; if A is invertible then x is also unique.

THEOREM 2. If $A: V \to V$ is a linear transformation such that for every $c \in V$ there is at most one $x \in V$ such that $x \ge 0$, $Ax + c \ge 0$, (x, Ax + c) = 0, then A is adequate and invertible.

Theorem 3. Let the linear transformation $A: V \to V$ be such that A_{JJ} is invertible for every subset J of $\{1, 2, \dots, n\}$. Suppose that for some $c \in V$ there is exactly one pair of vectors x, y satisfying:

(*)
$$y = Ax + c, x \ge 0, y \ge 0, (x, y) = 0$$

and that x + y > 0. Then at least one solution of (*) exists for every $c \in V$.

From this theorem follows immediately:

COROLLARY. If A_{JJ} is invertible for every J, and if for some c > 0 the only solution of (*) is x = 0, y = c, then at least one solution of (*) exists for every $c \in V$.

LEMMA. Each of the following properties of a linear transformation A implies the succeeding ones, and the last two are equivalent.

- a) $(Ae_i, e_i) \ge 0$ for all i, j and $(Ae_i, e_i) > 0$ for all i.
- b) For every J, there exists $p \in V_J$ such that $p \ge 0$, $A_{JJ}^* p > 0$.
- c) For every J, and every $u \in V_J$

$$u \ge 0$$
, $A_{JJ}u \le 0 \Rightarrow u = 0$.

d) For any $c \ge 0$, the sytem (*) is satisfied only if x = 0.

We add here that in this Lemma (c) also implies (b).

PROOF. Assume (c) and take its transpose which reads

$$u' \ge 0$$
, $u'A_{JJ}^* \le 0 \Rightarrow u' = 0$

then by a well known theorem [3; Theorem 2.10] (b) follows.

The following theorem is an immediate consequence of the last lemma and corollary, [1]:

THEOREM 4. If the linear transformation $A: V \to V$ is such that A_{JJ} is invertible for every subset J of $\{1, 2, \dots, n\}$, and if moreover A satisfies any of the conditions (a) to (d) of the Lemma, then at least one solution of the system (*) exists for every $c \in V$.

4. Ingleton's conjecture

It follows from Theorem 2 that the solution of the system (*) cannot be unique for every c in the following two cases,

Case I. A satisfies the hypotheses of Theorem 4 without being adequate. Case II. A satisfies the hypotheses of Theorem 3 without being adequate.

Ingleton conjectured ([1], p. 534, §4.5) that in both cases the maximal number of solutions of the system (*) in n dimensions is $2^{n}-1$.

Case I. The proof of the conjecture consists of the following three steps:

Step A. If A has the property that A_{JJ} is invertible for every subset J of $\{1, 2, \dots, n\}$ then the number 2^n is an upper bound for the number of solutions which the system (*) can have.

Step B. If A satisfies the hypotheses of Theorem 4 then the number $2^n - 1$ is an upper bound for the number of solutions which the system (*) can have.

Step C. There exists a matrix A and a vector c for which the system (*) has exactly $2^n - 1$ solutions.

PROOF.

Step A. The requirement (x, y) = 0 restricts the number of solutions that the system (*) can have.

Indeed if for some i $(1 \le i \le n)$ $x_i \ne 0$ then y_i must be zero and if for some j $(1 \le j \le n)$ $y_j \ne 0$ then x_j must be zero. Now, if a vector x has some p components equal to zero $(1 \le p \le n)$ then the pair x, y which forms a solution of the system (*) is uniquely determined, i.e. there does not exist another pair x', y' which is a solution of (*) and in which x' has the same p components equal to zero as x has.

Let us prove this assertion. Without loss of generality assume that x is a vector whose first p components x_1, x_2, \dots, x_p are zero and whose last (n - p) components x_{p+1}, \dots, x_n are different from zero.

Then (x, y) = 0 assures that the corresponding vector y has its last (n - p) components equal to zero.

The last (n - p) equations of the system y = Ax + c will then be:

$$\begin{bmatrix}
0 \\ \cdot \\ \cdot \\ 0
\end{bmatrix} = \begin{bmatrix}
A_{JJ} \\
A_{JJ}
\end{bmatrix} \begin{bmatrix}
x_{p+1} \\ \cdot \\ \cdot \\ x_n
\end{bmatrix} + \begin{bmatrix}
c_{p+1} \\ \cdot \\ \cdot \\ \cdot \\ c_n
\end{bmatrix}$$

where A_{JJ} is the lower right hand principal minor of order (n-p) of A.

The system (1) is a system of linear equations with a non-vanishing determinant and therefore $x_{p+1}, x_{p+2}, \dots, x_n$ are uniquely determined.

Then for $1 \le i \le p$ the first components of y are uniquely determined by:

(2)
$$y_i = \sum_{k=n+1}^{n} a_{ik} x_k + c_i, \quad 1 \le i \le p$$

Now a bound for the number of solutions of the system (*) is the number of all possible solutions under the restriction (x, y) = 0. Clearly, this bound is 2^n .

Step B. We claim that there does not exist a vector c for which the system (*) has 2^n solutions.

For if $c \ge 0$ then (*) has only one solution according to (d) of the lemma of the previous section.

If $c \ge 0$ then the solution x = 0, y = c is impossible since it means that $y \ge 0$, contrary to (*).

Therefore, if A satisfies the hypotheses of Theorem 4 the number $2^n - 1$ is an upper bound for the number of solutions of the system (*).

Step C. Take $A = (a_{ij})_{i,j=1}^n$ with $a_{ii} = 1$ for all i and $a_{ij} = 2$ for all i,j, $i \neq j$; and take $c = (c_i)_{i=1}^n$ with $c_i = -1$ for all i. We will prove that for these A and c:

- (i) A satisfies the hypotheses of Theorem 4 (and therefore also those of Theorem 3),
- (ii) A is not adequate, and (iii) the system (*) has exactly $2^n 1$ solutions.
- i) Denote the determinant of a principal submatrix of order J of the matrix A by A(J), then

(4)
$$A(J) = (-1)^{J-1}(2J-1) \neq 0$$

which means that A_{JJ} is invertible for every J.

A also satisfies (a) of the lemma of Section 3.

- ii) A is not adequate since all its principal minors of even order are negative.
- iii) We have to show that every pair of vectors of the form

$$x = (x_1, x_2, \dots, x_p, 0, \dots, 0), y = (0, \dots, 0, y_{p+1}, y_{p+2}, \dots, y_n),$$

which is a solution of y = Ax + c satisfies $x \ge 0$, $y \ge 0$.

The system y = Ax + c splits into two systems,

$$(5) 0 = A_{JJ}x_J + c_J$$

with |J| = p, and

(6)
$$y_i = 2 \left[\sum_{k=1}^p x_k \right] - 1, \quad i = p+1, p+2, \dots, n.$$

Solving the system (5) we get

$$x_i = \frac{1}{2n-1} \ge 0, \quad i = 1, \dots, p.$$

and the system (6) then gives

$$y_j = \frac{1}{2p-1} \ge 0, \quad j = p+1, \dots, n.$$
 Q.E.D.

REMARKS.

- 1) One can easily see that the maximal number of solutions for (*) under the discussed conditions is obtained not only for the data given in the proof of Step C, but also for many other data as for example: $A = (a_{ij})_{i,j=1}^n$ with $a_{ii} = 1$ for all i and $a_{ij} = k$ for all i, j $i \neq j$ and the vector $c = (c_i)_{i=1}^n$ with $c_i = -p$ for all i, where k and p are suitable natural numbers.
- 2) For the special case n=2 the following is true: For every matrix $A=(a_{ij})_{i,j=1}^2$ which satisfies
 - i) det $A_{JJ} \neq 0$ for every J,
 - ii) $a_{ij} \ge 0$ for all i, j and $a_{ii} > 0$ for all i,
 - iii) A is not adequate,

a vector c can be constructed so that the system (*) will attain its maximal number of solutions (i.e. three). The proof is a straightforward one and appears in [4].

Case II. Steps A and C of the proof of Case I hold also here but we did not manage to reduce the upper bound for the number of solutions of (*) to 2^n-1 . Using some results of Murty [5] it is possible to settle Case II partially.

DEFINITION [5; §2.16]. The vector c is called nondegenerate with respect to A if and only if for all solutions of y = Ax + c at most n of the 2n variables $\{x_i, y_i\}$ are zero.

THEOREM 5 [5; Th.6.2]. If A satisfies det $A_{JJ} \neq 0$ for every J then the number of solutions of (*) has the same parity (odd or even) for all c nondegenerate with respect to A.

Now, A satisfies the hypotheses of Theorem 3 means that for some c nondegenerate with respect to A there is a unique solution of the system (*). Then, according to Theorem 5, the number of solutions of (*) must be odd for every c nondegenerate with respect to A.

Thus for Case II the maximal number of solutions of (*) is $2^n - 1$ when the maximum is taken over the data $\{A, c\}$ where A is of case II and c is nondegenerate with respect to A.

5. Discussion

Consider the class of matrices A which satisfy:

- i) det $A_{IJ} \neq 0$ for every J, and
- ii) the system (*) has a solution for every $c \in \mathbb{R}^n$, and denote this class by G.

An invertible matrix is adequate if and only if it is a P-matrix (i.e. has det $A_{JJ} > 0$ for every J), see [1], [2]. Therefore, within the class G the adequate matrices are exactly all the P-matrices.

For a matrix A which is in G but not a P-matrix, (*) has a solution for every c but again according to Theorem 2 the solution of (*) cannot be unique for every c. This leads to the following

QUESTION. Is it true that for every matrix A in G which is not a P-matrix the maximal number of solutions of the system (*) is $2^n - 1$?

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